

Real time modeling of water infrastructure using hydraulic models and data assimilation

Smart Sustainable Cities seminar

DTU Lyngby

6th of February 2017

By

Asst. Prof.

Morten Borup

DTU Environment

Contents

- Detailed urban hydrological models (HIFI models)
 - Why online HIFI models
- The Ensemble Kalman Filter (EnKF)
- Surrogates of HIFI models

Detailed urban hydrological models (HIFI models)

Mike Urban (DHI) model of Avedøre

WWTP catchment

- 1707 sub-catchments
- 6601 Manholes
- 7749 Pipe & channel sections
- 40 Pumps
- 40 Basins
- Etc.

Can potentially be all-knowing:

Water levels, volumes, flows, concentrations - everywhere

The models can be made automatically

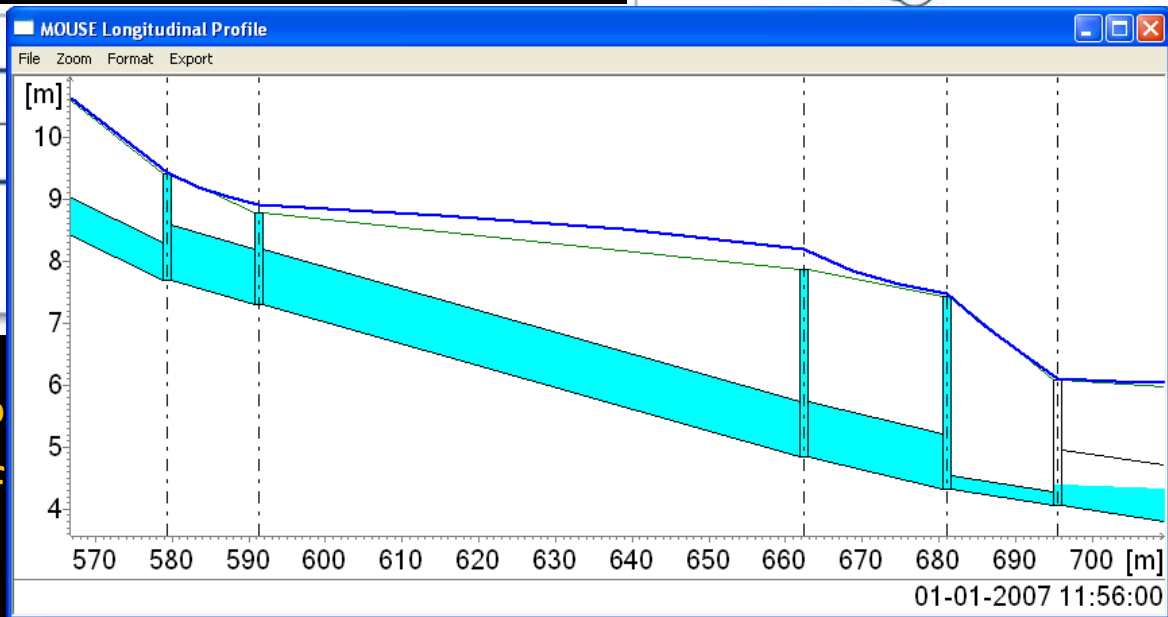
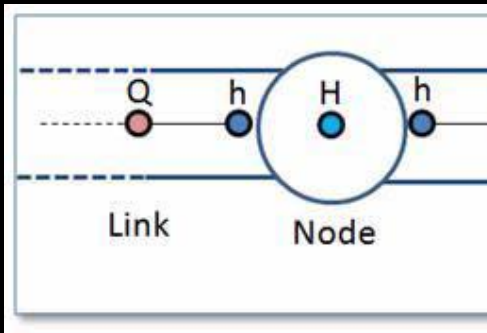
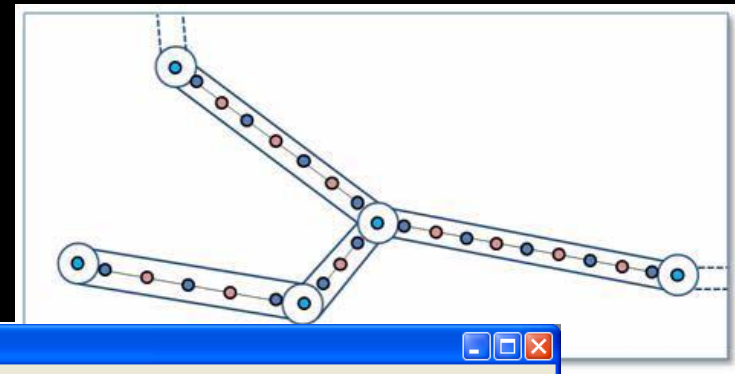
- If the asset data base is well maintained!

Can adapt to system changes (as opposed to data driven models)

5 km



Hydraulic computations



- Full 1D St. Venant equation
- Conservation of

Conservation of momentum:

$$\frac{\partial Q}{\partial t} + \frac{\partial \left(\alpha \frac{Q^2}{A} \right)}{\partial x} + gA \frac{\partial y}{\partial x} + g AI f = gAI_0$$

Potential of online HIFI model

- Warning system
- Real time control
- Online supervision of gauges
- Error detection

Not used because:

- **Computational cost**
- **Very uncertain rain input**
- **Lack of update algorithm's**



Detailed urban hydrological models (HIFI models)

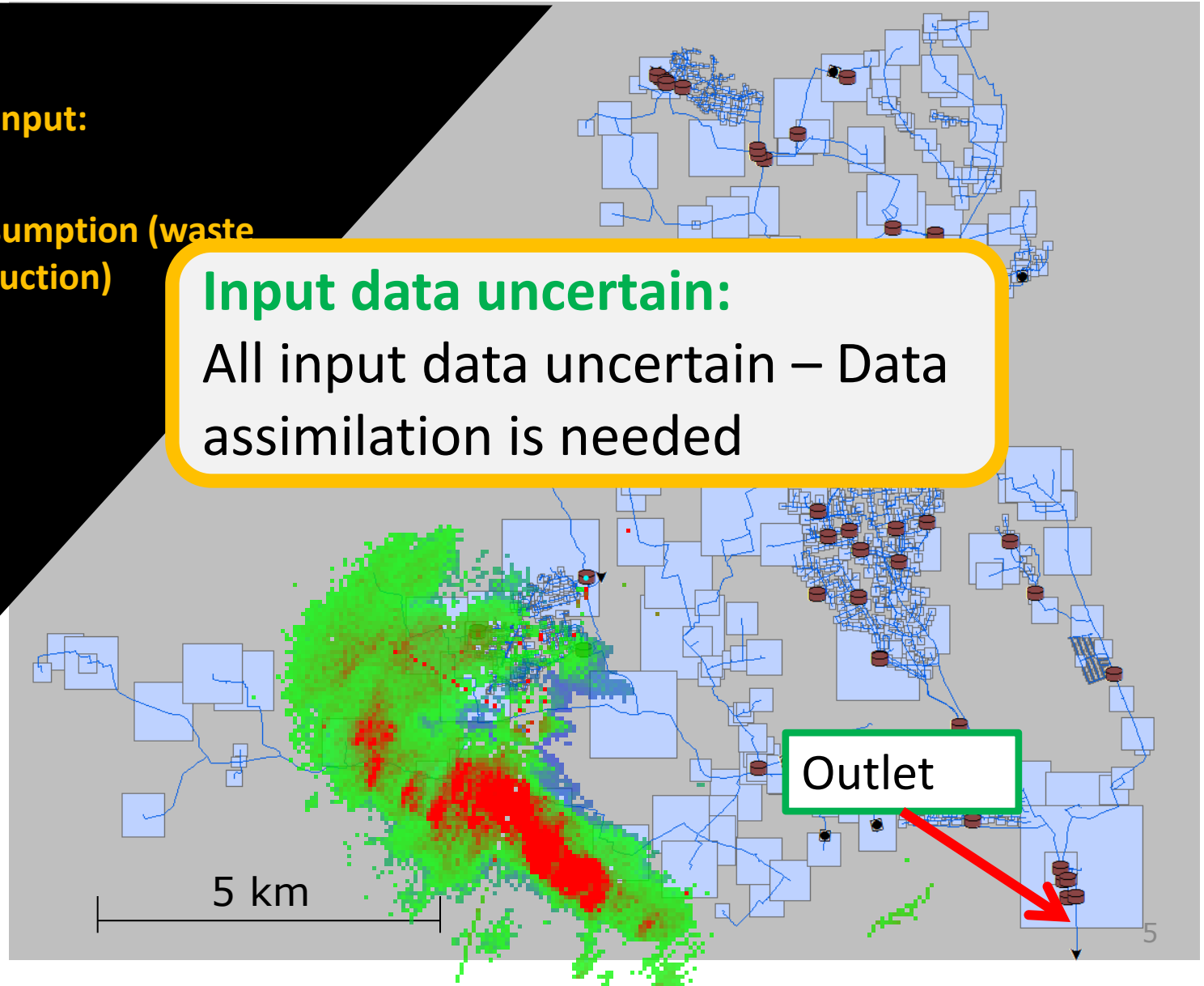
Main model input:

Rain data

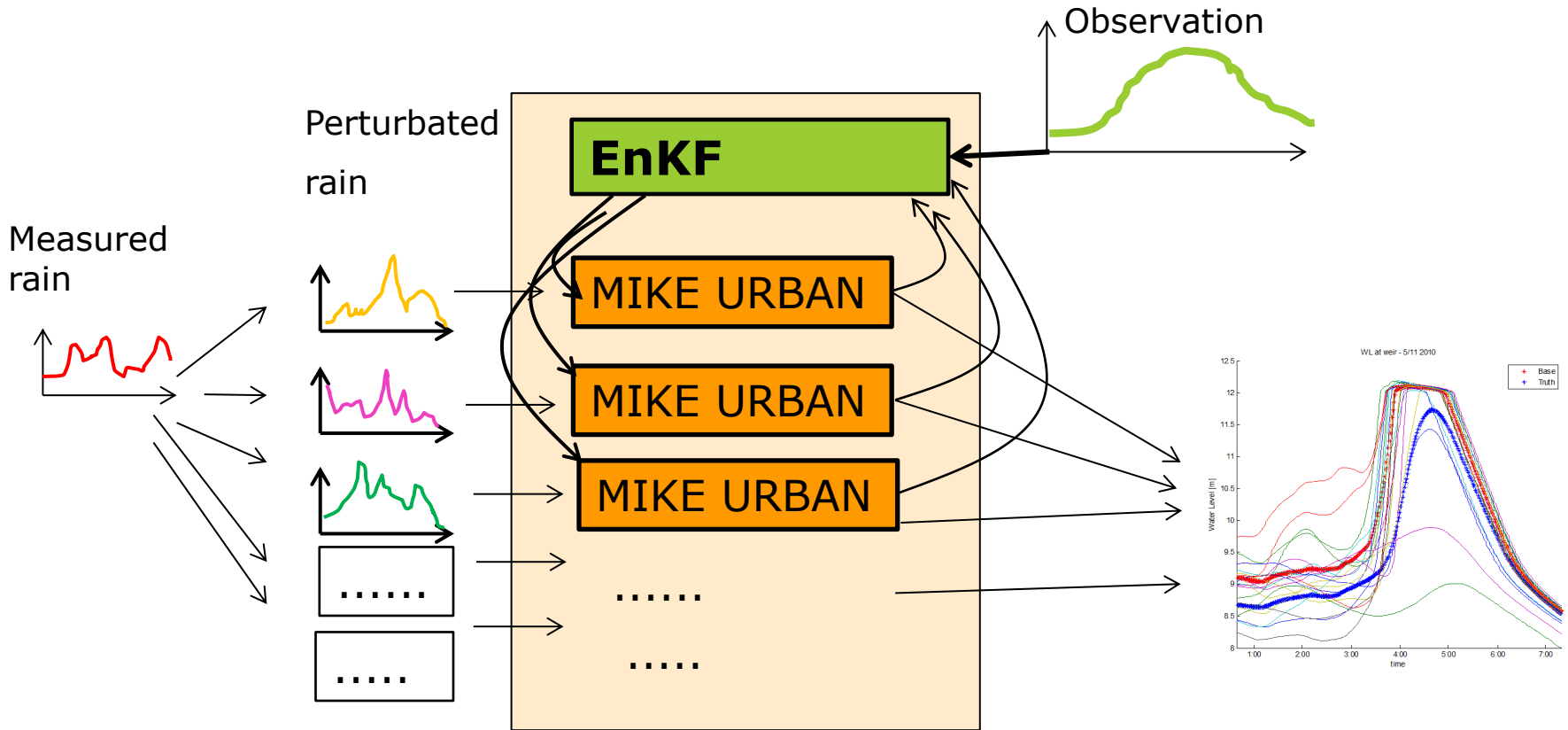
Water consumption (waste
water production)

Input data uncertain:

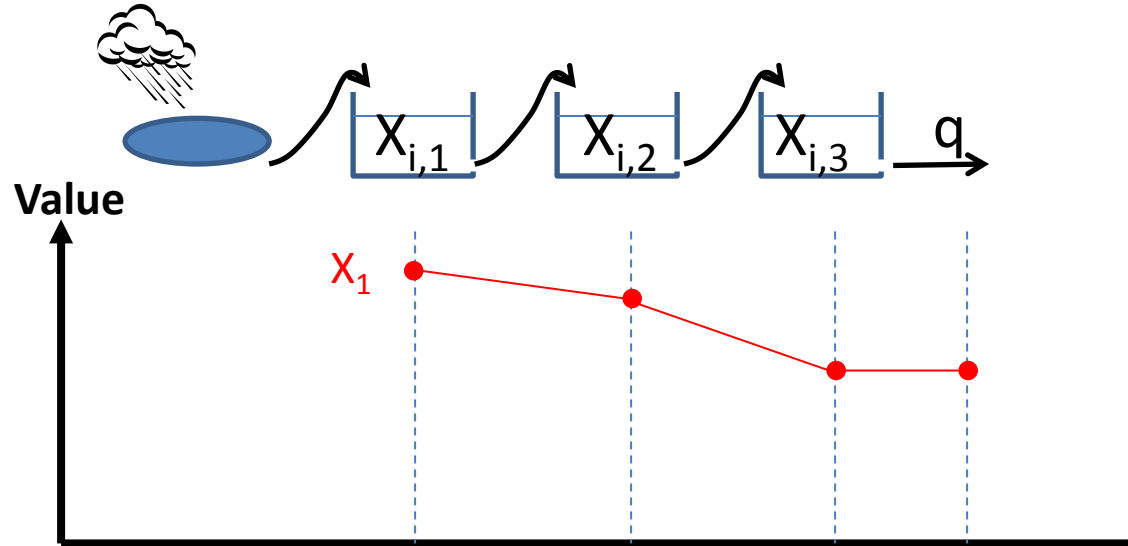
All input data uncertain – Data
assimilation is needed



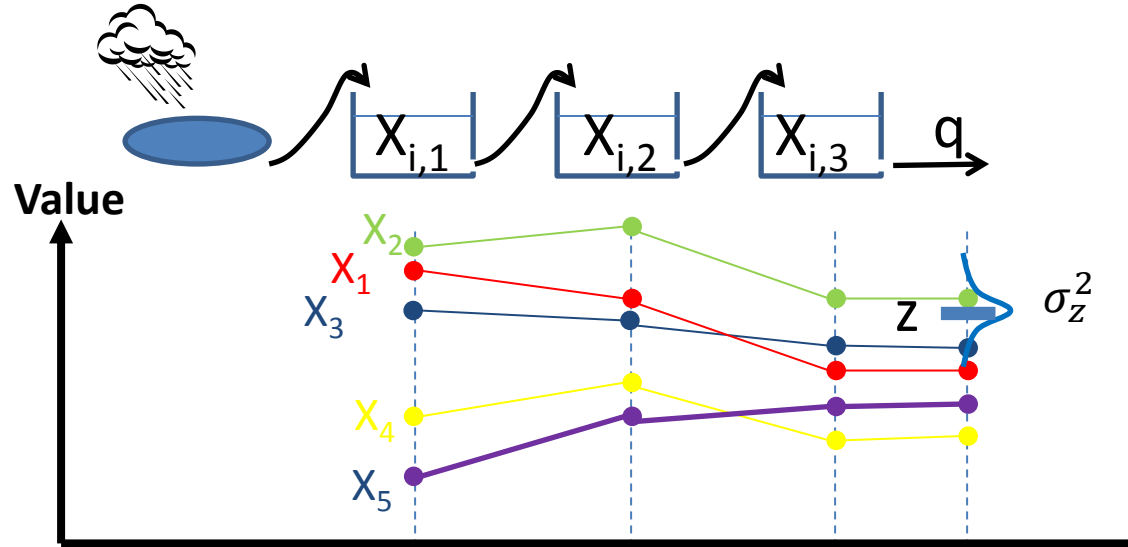
Ensemble based updating



Ensemble Kalman Filter



Ensemble Kalman Filter



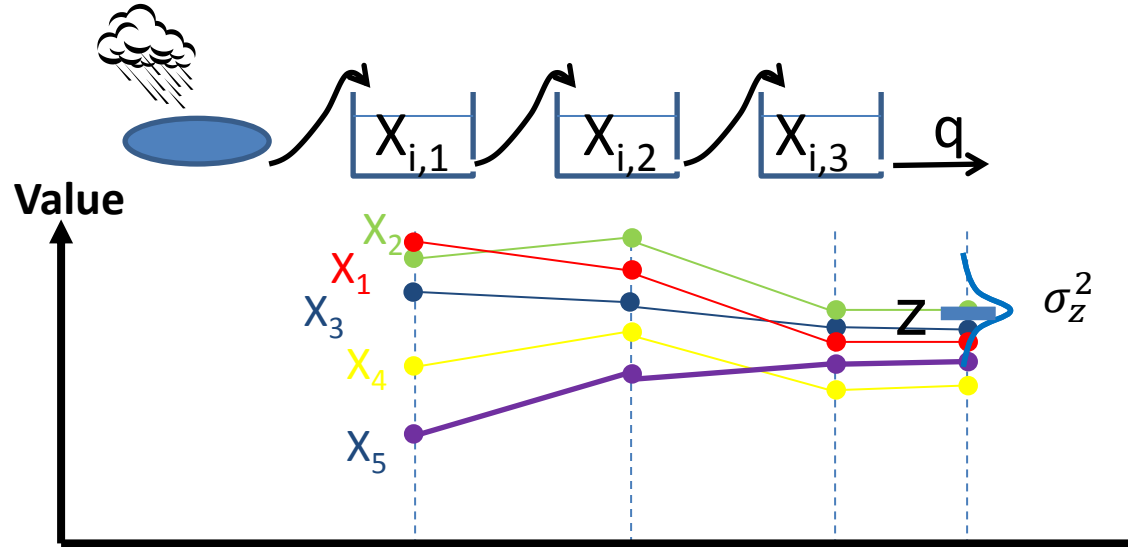
Ensemble of models used to represent state uncertainty (model error)

Estimate of the error covariance can be calculated directly from ensemble:

$$\sigma_{1,3} = \frac{1}{N-1} \sum_i^N (X_{i,1} - \bar{X}_{,1})(X_{i,3} - \bar{X}_{,3})$$

$$X_{1,3} = \widehat{X}_{1,3} + \frac{\sigma_{X_{1,3},q}}{\sigma_q^2 + \sigma_z^2} (z - q)$$

Ensemble Kalman Filter



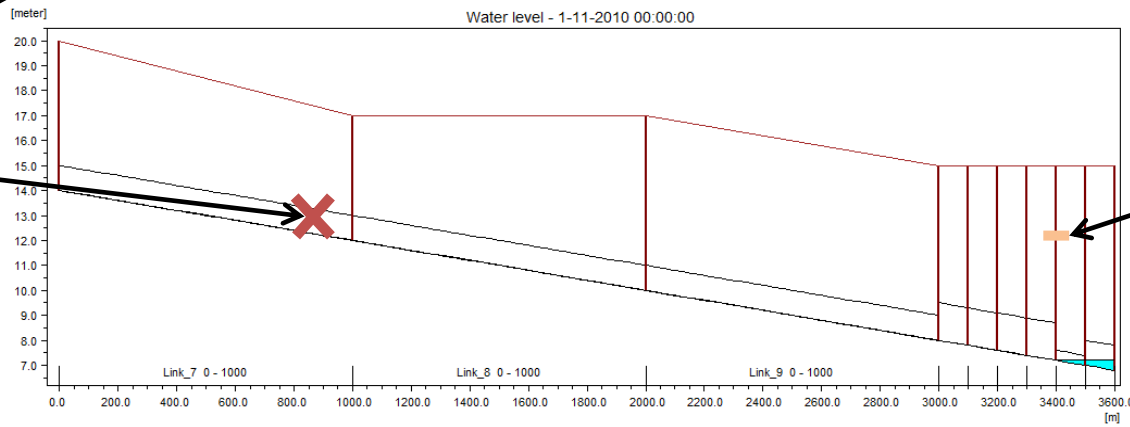
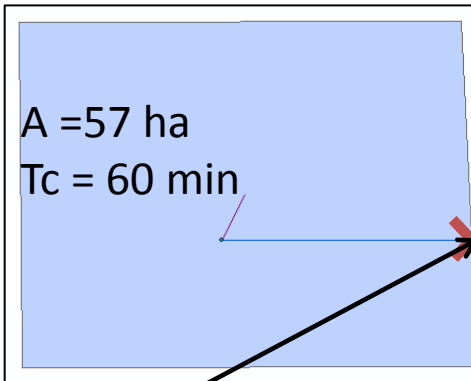
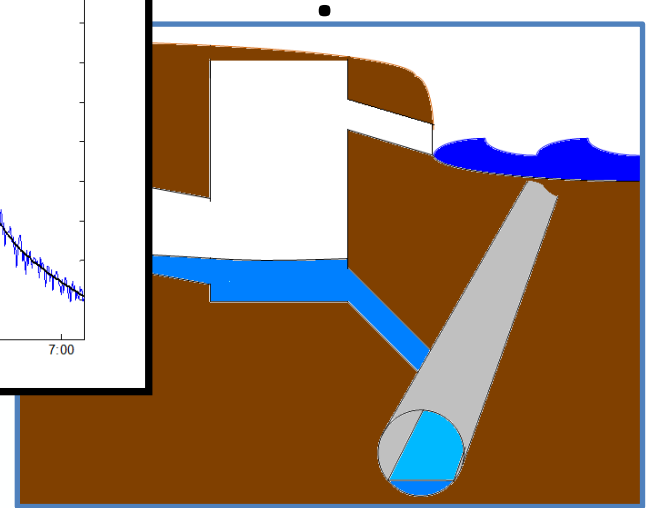
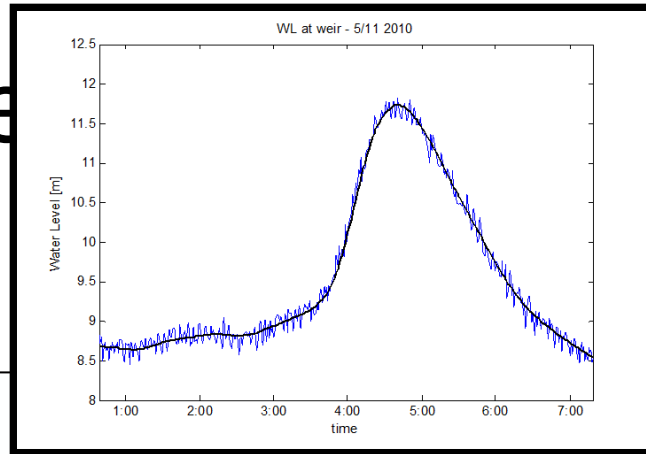
Ensemble of models used to represent state uncertainty (model error)

Estimate of the error covariance can be calculated directly from ensemble:

$$\sigma_{1,3} = \frac{1}{N-1} \sum_i^N (X_{i,1} - \bar{X}_{,1})(X_{i,3} - \bar{X}_{,3})$$

$$X_{1,3} = \widehat{X}_{1,3} + \frac{\sigma_{X_{1,3},q}}{\sigma_q^2 + \sigma_z^2} (z - q)$$

Model set



Point at Link 7

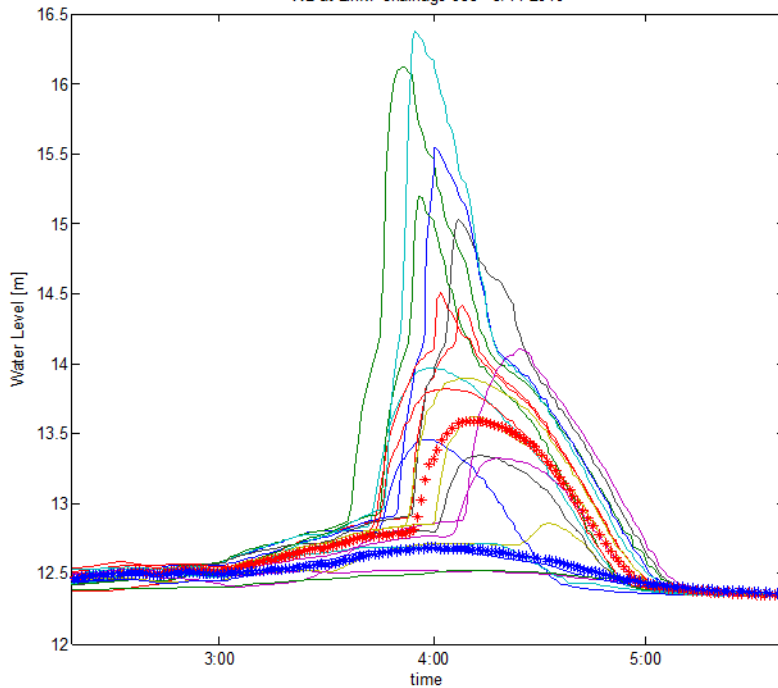
Weir

Situation without update

Ensemble of 20 – No update

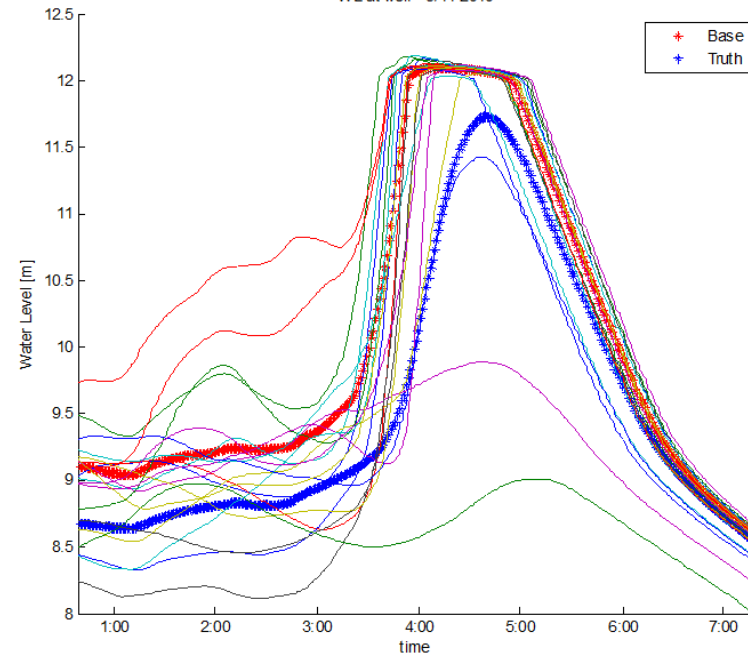
Link 7

WL at Link7 chainage 935 - 5/11 2010



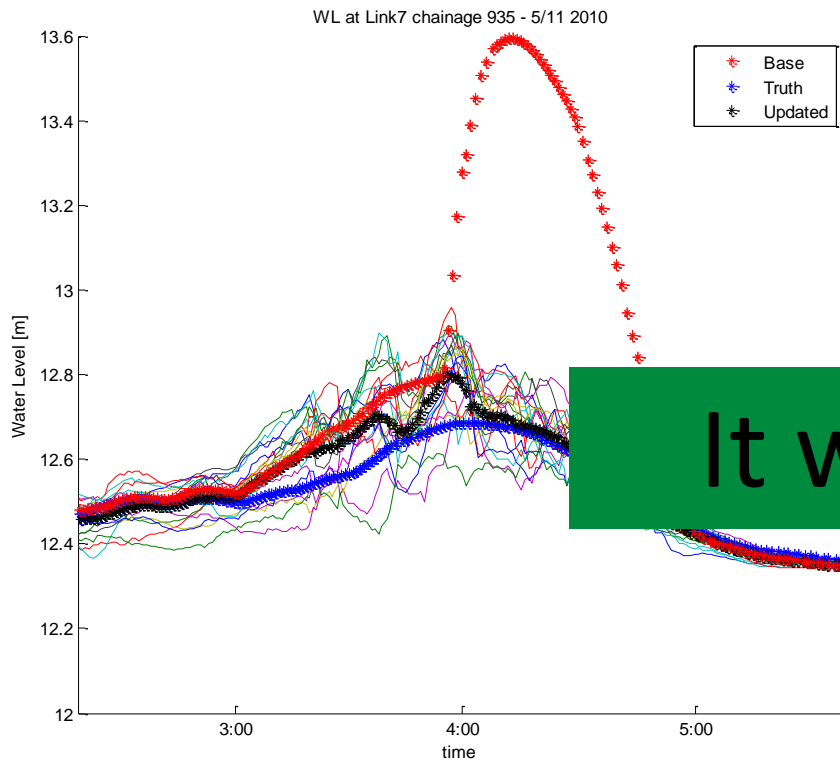
Weir

WL at weir - 5/11 2010

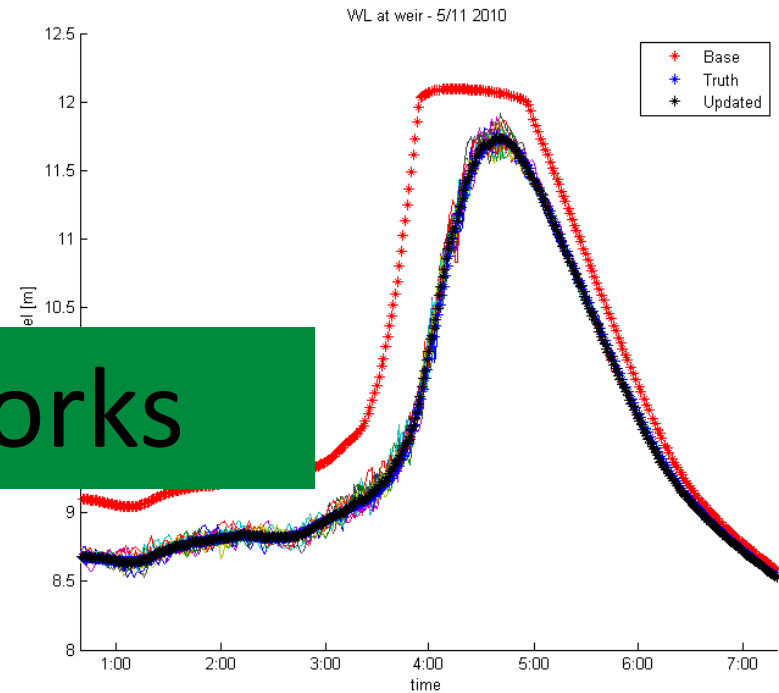


When updating using EnKF

Link 7



Weir



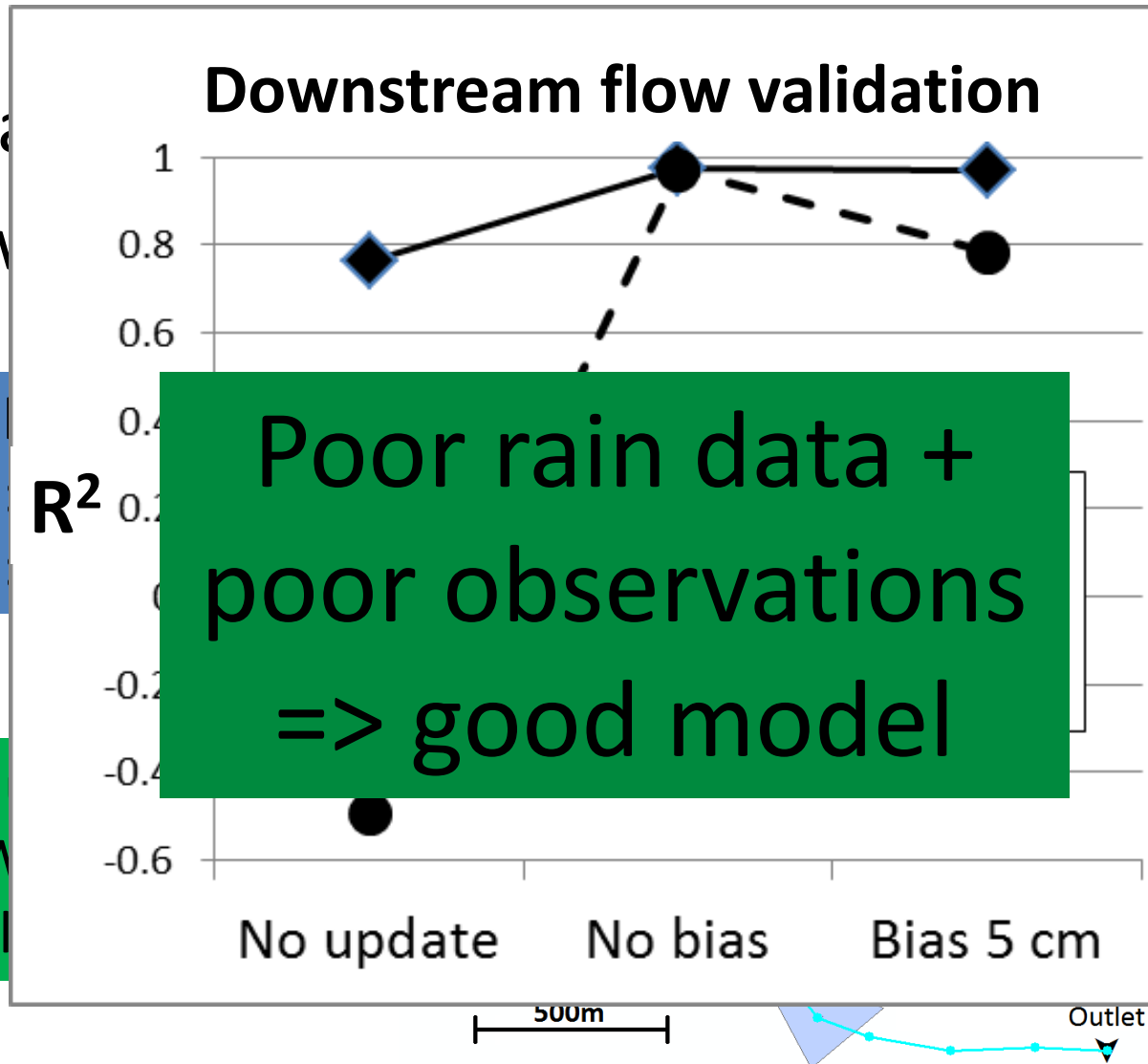
It works

Synthetic test on distributed system

- Update
- Down

Two rainfall
Scenario 1
Scenario 2

Two w/ga
No bias: W
Bias: + Col



Benefits in using EnKF for HIFI models

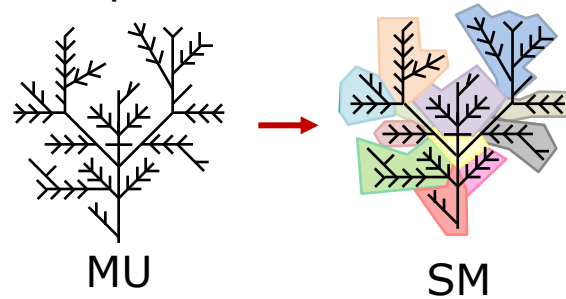
- Robust
- Flexible
- Good uncertainty estimates
- Can utilize ensemble input
- Can utilize most kinds of observations

Drawbacks:

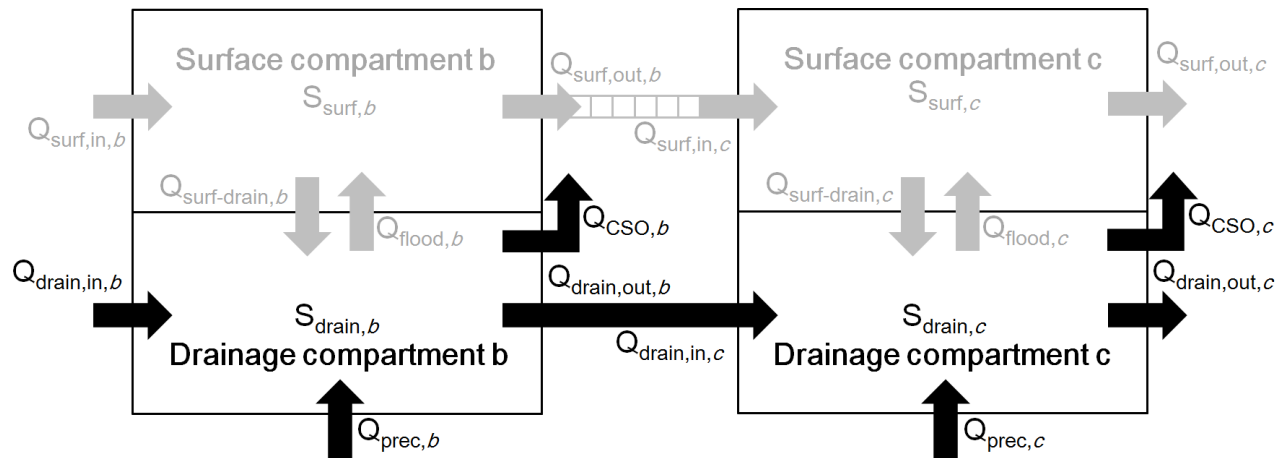
- computational cost

Making Surrogates of HIFI models

- Division of system into compartments:

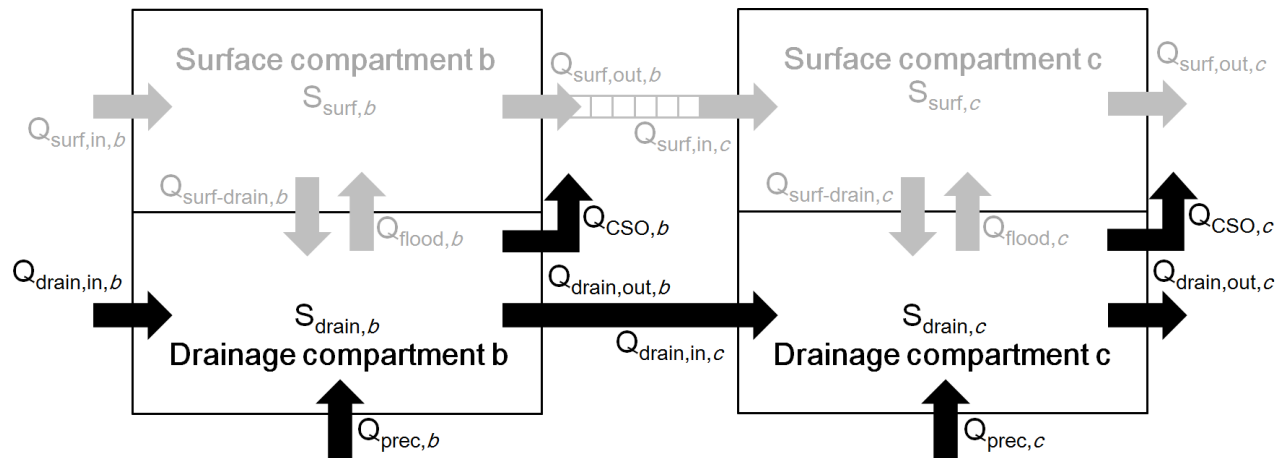
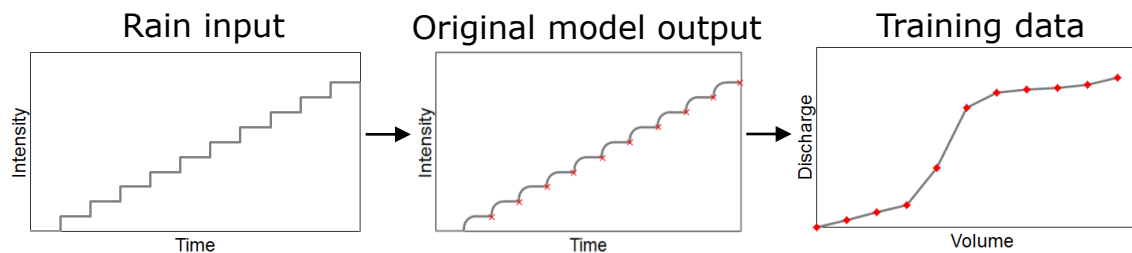


- Model volume of water with mass balance:

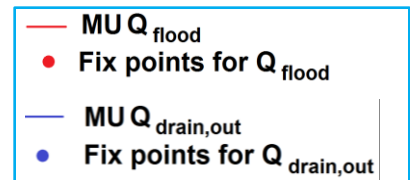
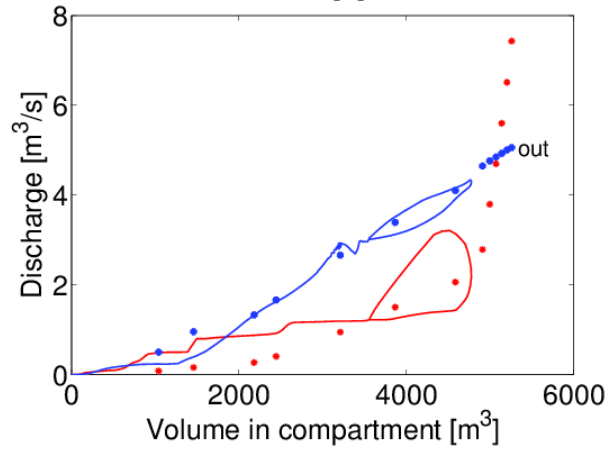
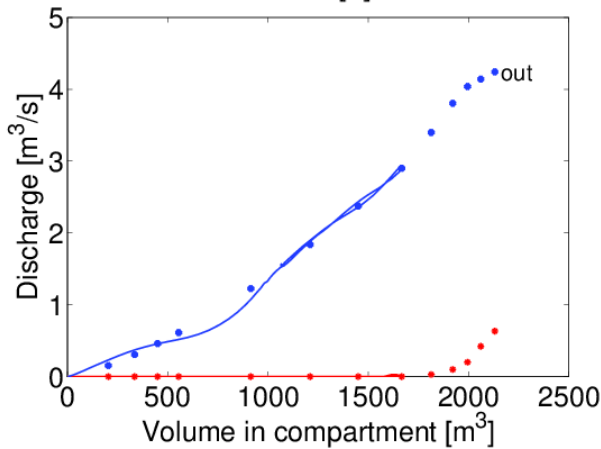
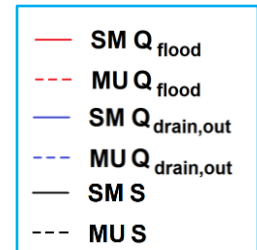
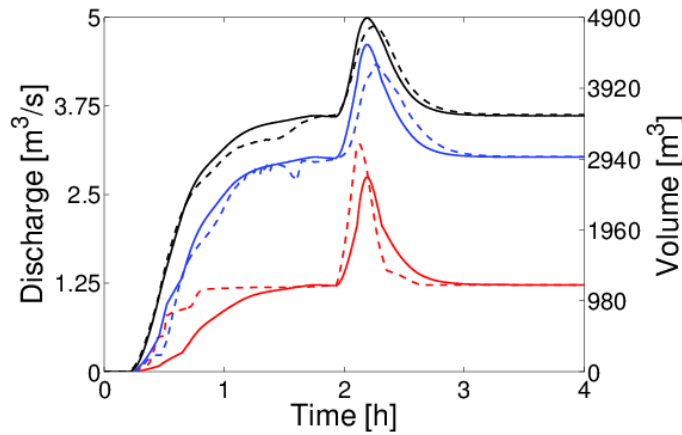
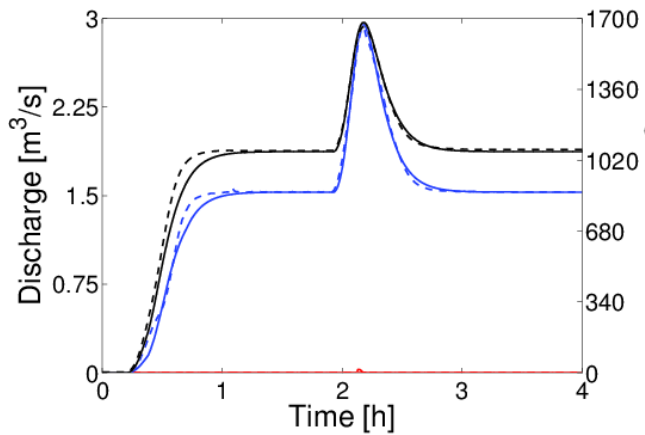


Training data for SM

- Vol-Q relationships are extracted from steady state values

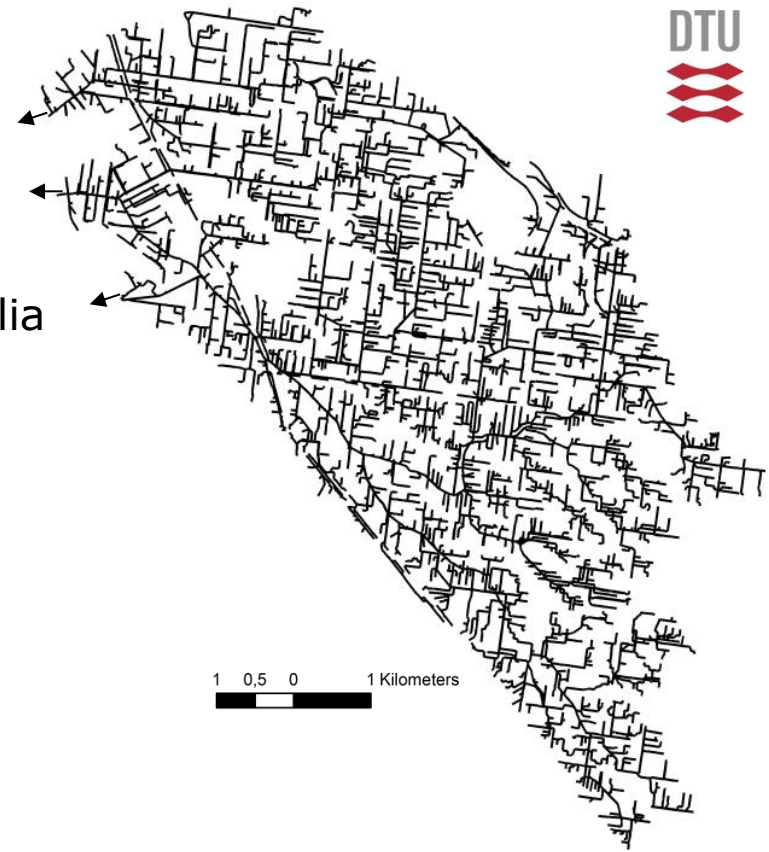


• Drainage system results



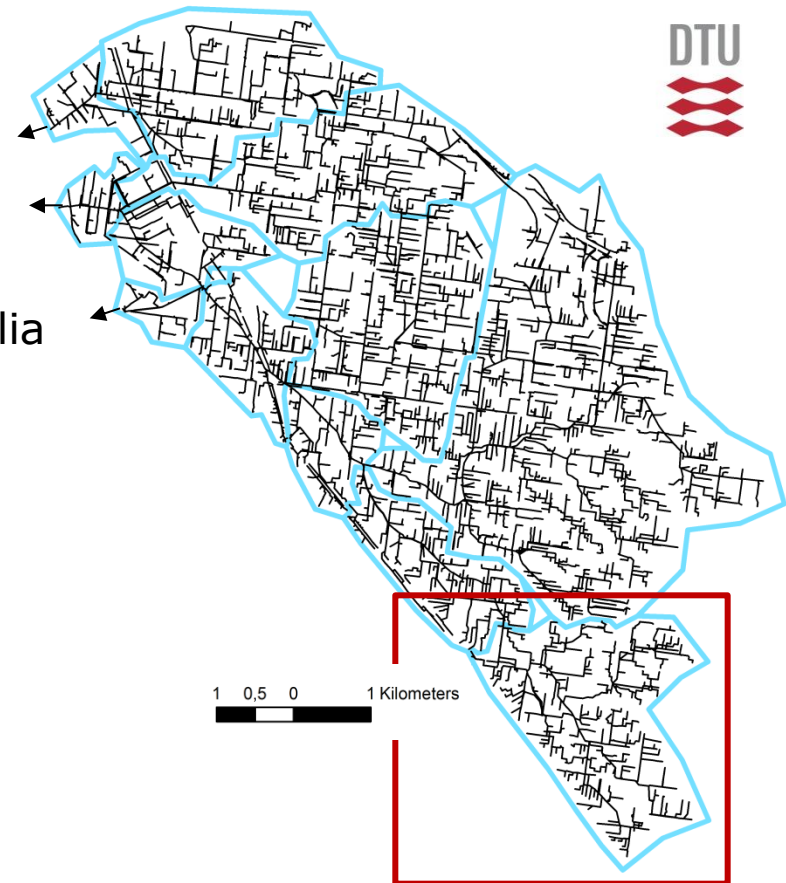
Preliminary results

- Elster Creek catchment, Melbourne, Australia



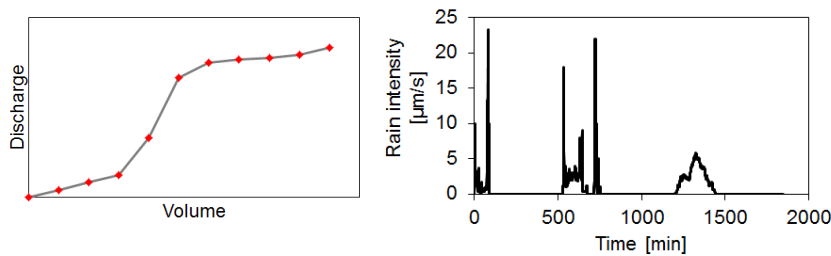
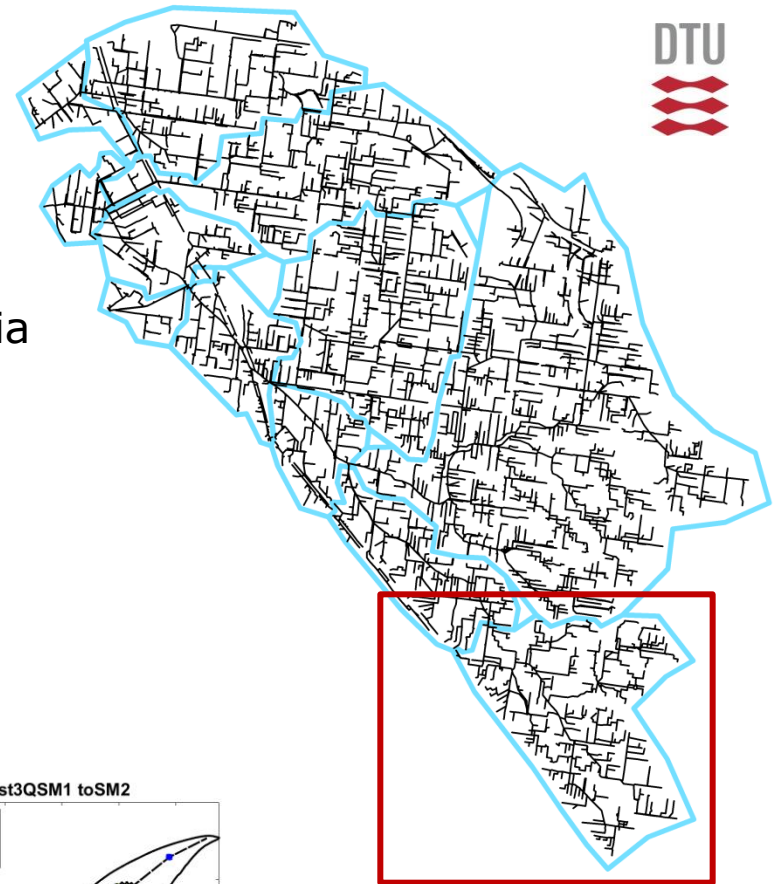
Preliminary results

- Elster Creek catchment, Melbourne, Australia

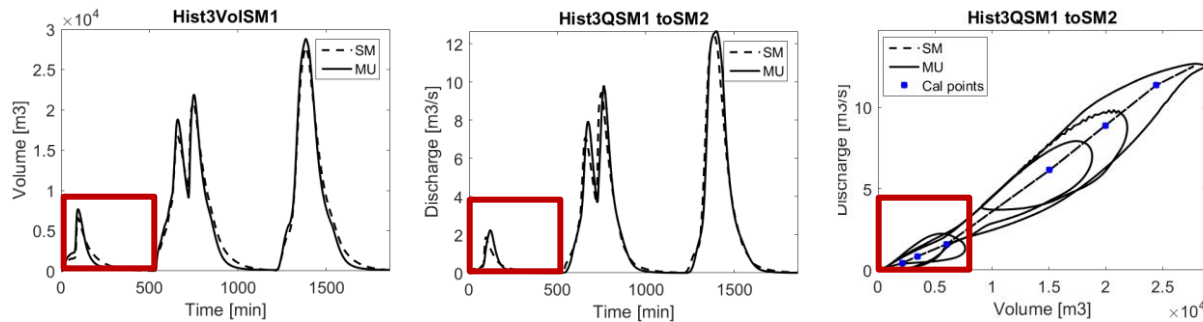


Preliminary results

- Elster Creek catchment, Melbourne, Australia
- Steady state training data

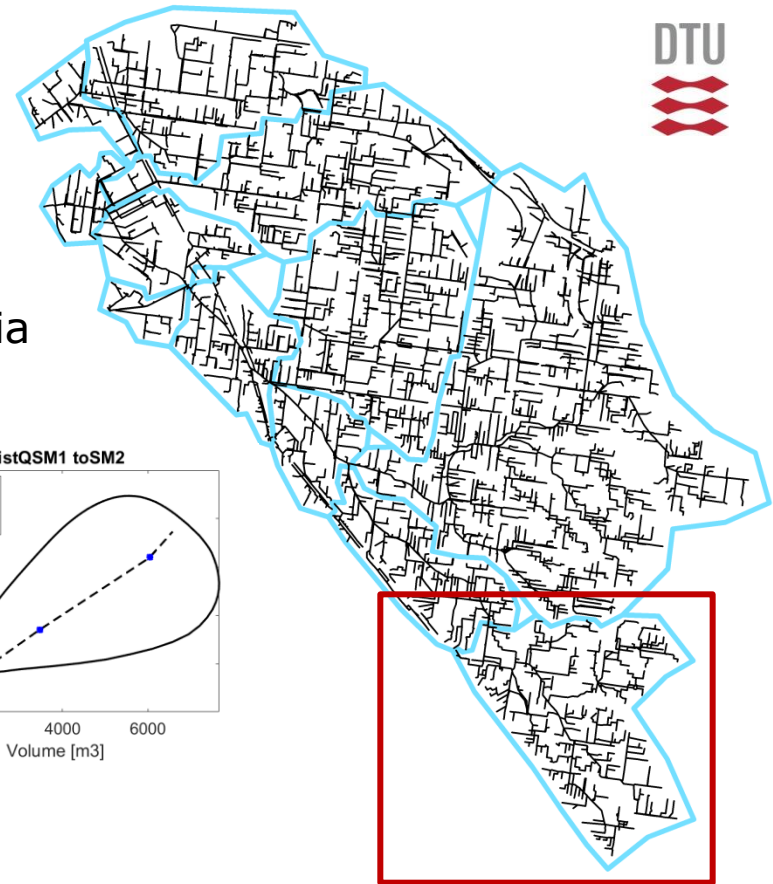
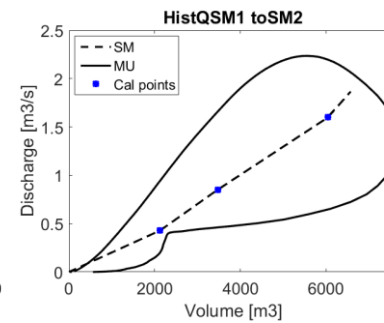
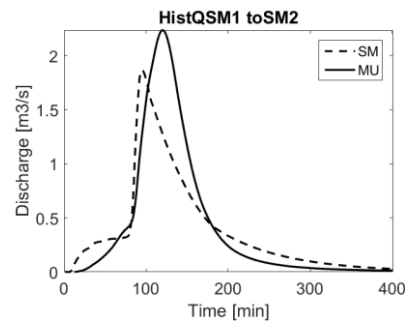
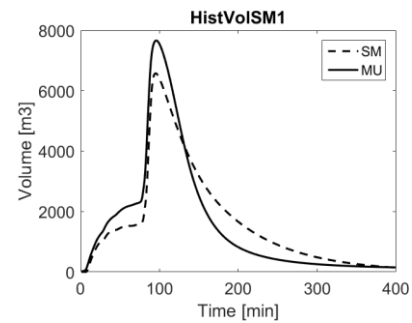


- SM output



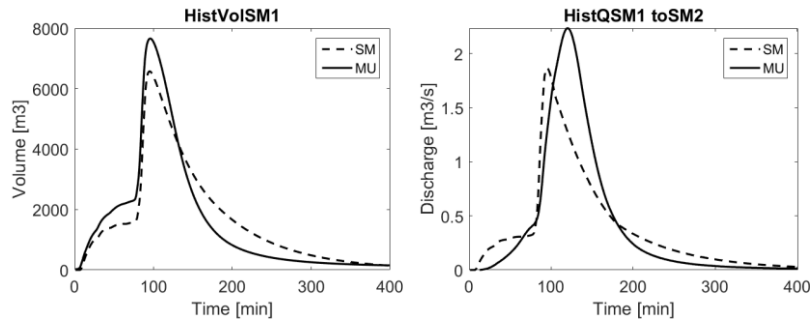
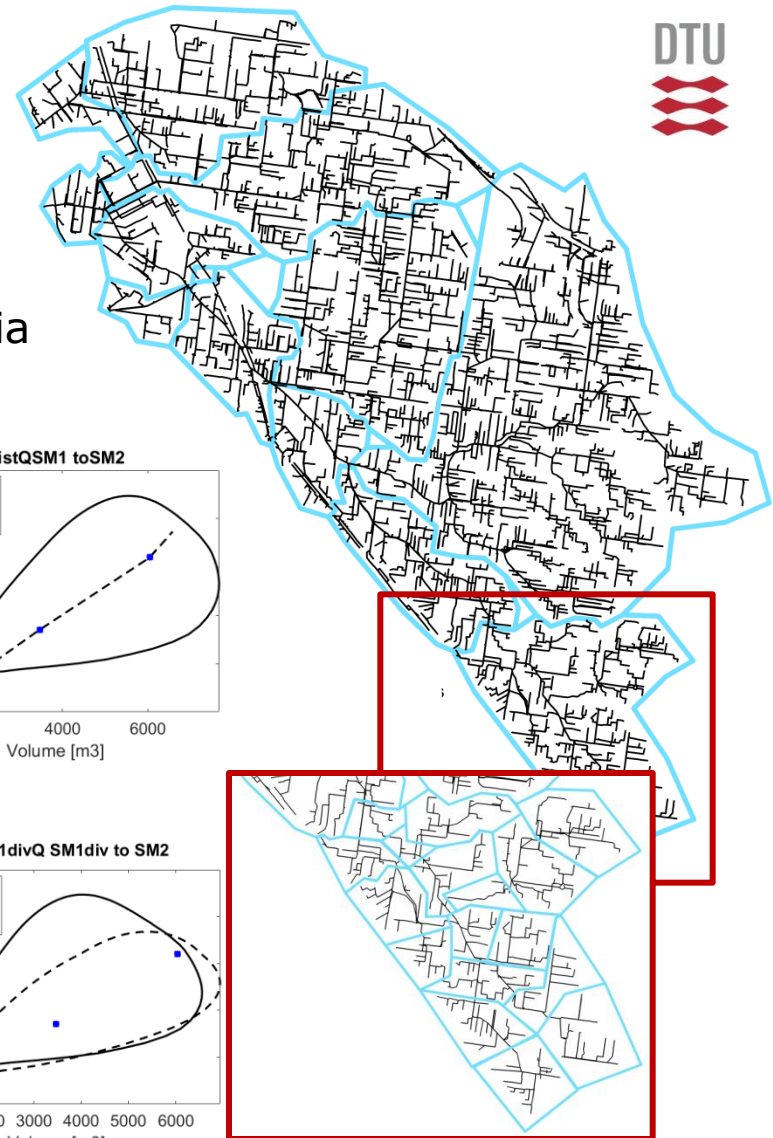
Preliminary results

- Elster Creek catchment, Melbourne, Australia
- Steady state training data

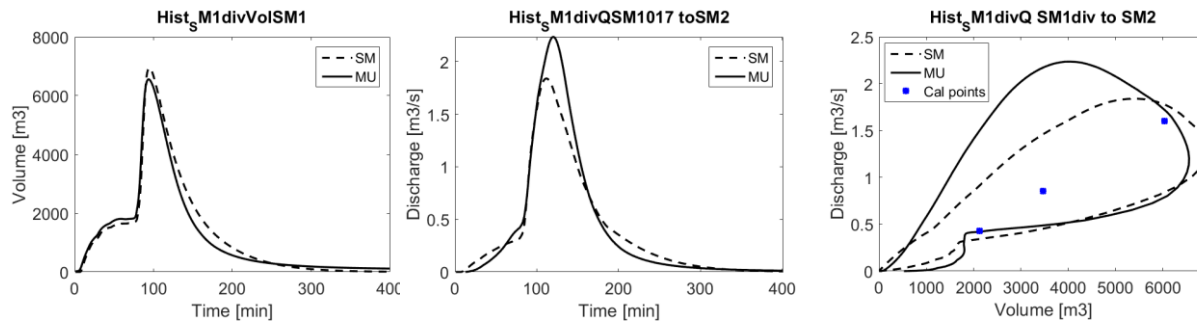


Preliminary results

- Elster Creek catchment, Melbourne, Australia
- Steady state training data



- Splitting compartment



Conclusions

- EnKF can be used to make online models with HIFI models
- Surrogate models can be made for HIFI models to achieve large reduction in computational costs.

Questions?